

Functional Data Structures

with Isabelle/HOL

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Part II

Functional Data Structures

Chapter 1

Binary Trees

- ① Binary Trees
- ② Basic Functions
- ③ Interlude: Arithmetic in Isabelle
- ④ More Basic Functions
- ⑤ Complete and Balanced Trees

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Library/Tree.thy

Binary trees

datatype *'a tree = Leaf | Node ('a tree) 'a ('a tree)*

Abbreviations:

$$\begin{aligned} \langle \rangle &\equiv \textit{Leaf} \\ \langle l, a, r \rangle &\equiv \textit{Node } l \ a \ r \end{aligned}$$

In the sequel: **tree = binary tree**

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Tree traversal

inorder :: 'a tree \Rightarrow 'a list

inorder $\langle \rangle = []$

inorder $\langle l, x, r \rangle = \text{inorder } l @ [x] @ \text{inorder } r$

preorder :: 'a tree \Rightarrow 'a list

preorder $\langle \rangle = []$

preorder $\langle l, x, r \rangle = x \# \text{preorder } l @ \text{preorder } r$

postorder :: 'a tree \Rightarrow 'a list

postorder $\langle \rangle = []$

postorder $\langle l, x, r \rangle = \text{postorder } l @ \text{postorder } r @ [x]$

Size

$size :: 'a\ tree \Rightarrow nat$

$$|\langle \rangle| = 0$$

$$|\langle l, _, r \rangle| = |l| + |r| + 1$$

$size1 :: 'a\ tree \Rightarrow nat$

$$|t|_1 = |t| + 1$$

\implies

$$|\langle \rangle|_1 = 1$$

$$|\langle l, x, r \rangle|_1 = |l|_1 + |r|_1$$

Lemma The number of leaves in t is $|t|_1$.

Warning: $|\cdot|$ and $|\cdot|_1$ only on slides

Height

$height :: 'a\ tree \Rightarrow nat$

$$h(\langle \rangle) = 0$$

$$h(\langle l, -, r \rangle) = \max(h(l)) (h(r)) + 1$$

Warning: $h(\cdot)$ only on slides

Lemma $h(t) \leq |t|$

Lemma $|t|_1 \leq 2^{h(t)}$

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③ Interlude: Arithmetic in Isabelle

Numeric Types

Chains of (In)Equations

Proof Automation

Numeric types: *nat*, *int*, *real*

Need conversion functions (inclusions):

$$\begin{aligned} \textit{int} &:: \textit{nat} \Rightarrow \textit{int} \\ \textit{real} &:: \textit{nat} \Rightarrow \textit{real} \\ \textit{real_of_int} &:: \textit{int} \Rightarrow \textit{real} \end{aligned}$$

If you need type *real*,
import theory *Complex_Main* instead of *Main*

Numeric types: *nat*, *int*, *real*

Isabelle inserts conversion functions automatically

(with theory *Complex_Main*)

If there are multiple correct completions,

Isabelle chooses an **arbitrary** one

Examples

$$(i::int) + (n::nat) \rightsquigarrow i + int\ n$$

$$((n::nat) + n) :: real \rightsquigarrow real(n+n), real\ n + real\ n$$

Numeric types: *nat*, *int*, *real*

Coercion in the other direction:

$$\begin{aligned} \textit{nat} &:: \textit{int} \Rightarrow \textit{nat} \\ \textit{floor} &:: \textit{real} \Rightarrow \textit{int} \\ \textit{ceiling} &:: \textit{real} \Rightarrow \textit{int} \end{aligned}$$

Overloaded arithmetic operations

- Numbers are overloaded: $0, 1, 2, \dots :: 'a$
- Basic arithmetic functions are overloaded:
 $op +, op -, op * :: 'a \Rightarrow 'a \Rightarrow 'a$
 $- :: 'a \Rightarrow 'a$
- Division on *nat* and *int*:
 $op div, op mod :: 'a \Rightarrow 'a \Rightarrow 'a$
- Division on *real*: $op / :: 'a \Rightarrow 'a \Rightarrow 'a$
- Exponentiation with *nat*: $op ^ :: 'a \Rightarrow nat \Rightarrow 'a$
- Exponentiation with *real*: $op powr :: 'a \Rightarrow 'a \Rightarrow 'a$
- Absolute value: $abs :: 'a \Rightarrow 'a$

③ Interlude: Arithmetic in Isabelle

Numeric Types

Chains of (In)Equations

Proof Automation

Chains of equations

Textbook proof

$$\begin{aligned}t_1 &= t_2 && \langle \text{justification} \rangle \\ &= t_3 && \langle \text{justification} \rangle \\ &\vdots \\ &= t_n && \langle \text{justification} \rangle\end{aligned}$$

In Isabelle:

have " $t_1 = t_2$ " \langle proof \rangle
also have " $\dots = t_3$ " \langle proof \rangle
 \vdots
also have " $\dots = t_n$ " \langle proof \rangle
finally have " $t_1 = t_n$ " .

"..." is literally **three dots**

Chains of equations and inequations

Instead of $=$ you may also use \leq and $<$.

Example

have " $t_1 < t_2$ " ⟨proof⟩

also have "... = t_3 " ⟨proof⟩

⋮

also have "... $\leq t_n$ " ⟨proof⟩

finally have " $t_1 < t_n$ " .

How to interpret “...”

have " $t_1 \leq t_2$ " ⟨proof⟩

also have "... = t_3 " ⟨proof⟩

Here “...” is internally replaced by t_2

In general, if *this* is the formula $p \ t_1 \ t_2$ where p is some constant, then “...” stands for t_2 .

③ Interlude: Arithmetic in Isabelle

Numeric Types

Chains of (In)Equations

Proof Automation

Linear formulas

Only:

variables

numbers

number * variable

+, -

=, \leq , <

\neg , \wedge , \vee , \longrightarrow , \longleftrightarrow

Examples

Linear: $3 * x + 5 * y \leq z \longrightarrow x < z$

Nonlinear: $x \leq x * x$

Extended linear formulas

Also allowed:

min, max

even, odd

t div n, t mod n where *n* is a number

conversion functions

nat, floor, ceiling, abs

Automatic proof of arithmetic formulas

by *arith*

Proof method *arith* tries to solve arithmetic formulas.

- Succeeds or fails
- Decision procedure for extended linear formulas; for types *nat* and *int*, the extended linear formulas may also contain \forall and \exists
- Nonlinear subformulas are viewed as (new) variables; for example, $x \leq x * x$ is viewed as $x \leq y$

Automatic proof of arithmetic formulas

by (*simp add: algebra_simps*)

- The lemmas list *algebra_simps* helps to simplify arithmetic formulas
- It applies associativity, commutativity and distributivity of $+$ and $*$.
- This may prove the formula, may make it simpler, or may make it unreadable.
- It is a decision procedure for equations over rings (e.g. *int*)

Automatic proof of arithmetic formulas

by (*simp add: field_simps*)

- The lemmas list *field_simps* extends *algebra_simps* by rules for /
- Can only cancel common terms in a quotient, e.g. $x * y / (x * z)$, if $x \neq 0$ can be proved.

End of interlude, back to trees . . .

Tree.thy

$$|t|_1 \leq 2^{h(t)}$$

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Minimal height

$min_height :: 'a\ tree \Rightarrow nat$

$$mh(\langle \rangle) = 0$$

$$mh(\langle l, -, r \rangle) = \min (mh(l)) (mh(r)) + 1$$

Warning: $mh(\cdot)$ only on slides

Lemma $mh(t) \leq h(t)$

Lemma $2^{mh(t)} \leq |t|_1$

Internal path length

$ipl :: 'a \text{ tree} \Rightarrow \text{nat}$

$ipl \langle \rangle = 0$

$ipl \langle l, _ , r \rangle = ipl \ l + |l| + ipl \ r + |r|$

Why relevant?

Upper bound?

- ① Binary Trees
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Complete tree

$complete :: 'a\ tree \Rightarrow bool$

$complete \langle \rangle = True$

$complete \langle l, _, r \rangle =$

$(complete\ l \wedge complete\ r \wedge h(l) = h(r))$

Lemma $complete\ t = (mh(t) = h(t))$

Lemma $complete\ t \Longrightarrow |t|_1 = 2^{h(t)}$

Lemma $|t|_1 = 2^{h(t)} \Longrightarrow complete\ t$

Lemma $|t|_1 = 2^{mh(t)} \Longrightarrow complete\ t$

Corollary $\neg complete\ t \Longrightarrow |t|_1 < 2^{h(t)}$

Corollary $\neg complete\ t \Longrightarrow 2^{mh(t)} < |t|_1$

Complete tree: ipl

Lemma A complete tree of height h has internal path length $(h - 2) * 2^h + 2$.

In a search tree, finding the node labelled x takes as many steps as the path from the root to x is long.

Thus the average time to find an element that is in the tree is $ipl\ t / |t|$.

Lemma Let t be a complete search tree of height h . The average time to find a random element that is in the tree is asymptotically $h - 2$ (as h approaches ∞):

$$ipl\ t / |t| \sim h - 2$$

Complete tree: *ipl*

A problem: $(h - 2) * 2^h + 2$ is only correct if interpreted over type *int*, not *nat*.

Correct version:

Lemma *complete* $t \implies$

$$\text{int } (\text{ipl } t) = (\text{int } (h(t)) - 2) * 2^{h(t)} + 2$$

We do not cover the Isabelle formalization of limits.

Balanced tree

balanced :: 'a tree \Rightarrow bool

balanced t = (h(t) - mh(t) \leq 1)

Balanced trees have optimal height:

Lemma *If* balanced t \wedge |t| \leq |t'| *then* h(t) \leq h(t').

Warning

- The terms *complete* and *balanced* are not defined uniquely in the literature.
- For example, Knuth calls *complete* what we call *balanced*.

Chapter 2

Search Trees

⑥ Unbalanced BST

⑦ AVL Trees

⑧ Red-Black Trees

Most of the material focuses on
BSTs = binary search trees

BSTs represent sets

Any tree represents a set:

$set_tree :: 'a\ tree \Rightarrow 'a\ set$

$set_tree\ \langle \rangle = \{\}$

$set_tree\ \langle l, x, r \rangle = set_tree\ l \cup \{x\} \cup set_tree\ r$

A BST represents a set that can be searched in time $O(h(t))$

Function set_tree is called an *abstraction function* because it maps the implementation to the abstract mathematical object

bst

bst :: 'a tree \Rightarrow bool

bst $\langle \rangle$ = True

bst $\langle l, a, r \rangle$ =

(*bst* *l* \wedge *bst* *r* \wedge

($\forall x \in \text{set_tree } l. x < a$) \wedge

($\forall x \in \text{set_tree } r. a < x$))

Type 'a must be in class *linorder* ('a :: *linorder*) where *linorder* are *linear orders* (also called *total orders*).

Note: *nat*, *int* and *real* are in class *linorder*

Interface

An implementation of sets of elements of type $'a$ must provide

- An implementation type $'s$
- $empty :: 's$
- $insert :: 'a \Rightarrow 's \Rightarrow 's$
- $delete :: 'a \Rightarrow 's \Rightarrow 's$
- $isin :: 's \Rightarrow 'a \Rightarrow bool$

Alternative interface

Instead of a set, a search tree can also implement a `map` from `'a` to `'b`:

- An implementation type `'m`
- `empty :: 'm`
- `update :: 'a ⇒ 'b ⇒ 'm ⇒ 'm`
- `delete :: 'a ⇒ 'm ⇒ 'm`
- `lookup :: 'm ⇒ 'a ⇒ 'b option`

Sets are a special case of maps

Comparison of elements

We assume that the element type $'a$ is a linear order

Instead of using $<$ and \leq directly:

datatype $cmp_val = LT \mid EQ \mid GT$

$cmp\ x\ y =$
(if $x < y$ then LT else if $x = y$ then EQ else GT)

⑥ Unbalanced BST

⑦ AVL Trees

⑧ Red-Black Trees

Implementation

Implementation type: *'a tree*

empty = Leaf

insert x ⟨⟩ = ⟨⟨⟩, x, ⟨⟩⟩

insert x ⟨l, a, r⟩ = (case cmp x a of
 LT ⇒ ⟨insert x l, a, r⟩
 | EQ ⇒ ⟨l, a, r⟩
 | GT ⇒ ⟨l, a, insert x r⟩)

Implementation

isin $\langle \rangle$ $x = False$

isin $\langle l, a, r \rangle$ $x =$ (case *cmp* x a of
 LT \Rightarrow *isin* l x
 | *EQ* \Rightarrow *True*
 | *GT* \Rightarrow *isin* r x)

Implementation

```
delete x  $\langle \rangle$  =  $\langle \rangle$   
delete x  $\langle l, a, r \rangle$  =  
(case cmp x a of  
  LT  $\Rightarrow$   $\langle$ delete x l, a, r $\rangle$   
  | EQ  $\Rightarrow$  if  $r = \langle \rangle$  then l  
              else let  $(a', r') = \text{del\_min } r$  in  $\langle l, a', r' \rangle$   
  | GT  $\Rightarrow$   $\langle l, a, \text{delete } x r \rangle$ )
```

```
del_min  $\langle l, a, r \rangle$  =  
(if  $l = \langle \rangle$  then  $(a, r)$   
  else let  $(x, l') = \text{del\_min } l$  in  $(x, \langle l', a, r \rangle)$ )
```

⑥ Unbalanced BST

Correctness

Correctness Proof Method Based on Sorted Lists

Why is this implementation correct?

Because *empty* *insert* *delete* *isin*
simulate $\{\}$ $\cup \{.\}$ $- \{.\}$ \in :

$$\text{set_tree } \text{empty} = \{\}$$

$$\text{set_tree } (\text{insert } x \ t) = \text{set_tree } t \cup \{x\}$$

$$\text{set_tree } (\text{delete } x \ t) = \text{set_tree } t - \{x\}$$

$$\text{isin } t \ x = (x \in \text{set_tree } t)$$

Under the assumption *bst* *t*

Also: *bst* must be invariant

bst empty

bst t \implies *bst (insert x t)*

bst t \implies *bst (delete x t)*

⑥ Unbalanced BST

Correctness

Correctness Proof Method Based on Sorted Lists

sorted :: 'a list \Rightarrow bool

sorted [] = True

sorted [x] = True

sorted (x # y # zs) = (x < y \wedge *sorted* (y # zs))

No duplicates!

Structural invariant

The proof method works not just for unbalanced trees.
We assume that there is some structural invariant on the search tree:

inv : 's \Rightarrow bool

e.g. some balance criterion.

Correctness of *insert*

$$\text{inv } t \wedge \text{sorted } (\text{inorder } t) \implies \\ \text{inorder } (\text{insert } x \ t) = \text{ins_list } x \ (\text{inorder } t)$$

where

$$\text{ins_list} :: 'a \Rightarrow 'a \text{ list} \Rightarrow 'a \text{ list}$$

inserts an element into a sorted list.

Also covers preservation of *bst*

Correctness of *delete*

$$\text{inv } t \wedge \text{sorted } (\text{inorder } t) \implies \\ \text{inorder } (\text{delete } x \ t) = \text{del_list } x \ (\text{inorder } t)$$

where

$$\text{del_list} :: 'a \Rightarrow 'a \text{ list} \Rightarrow 'a \text{ list}$$

deletes an element from a sorted list.

Also covers preservation of *bst*

Correctness of *isin*

$$\text{inv } t \wedge \text{sorted } (\text{inorder } t) \implies \\ \text{isin } t \ x = (x \in \text{elems } (\text{inorder } t))$$

where

elems :: 'a list \Rightarrow 'a set

converts a list into a set.

⑥ Unbalanced BST

⑦ AVL Trees

⑧ Red-Black Trees

Data_Structures/AVL_Set.thy

⑥ Unbalanced BST

⑦ AVL Trees

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Data_Structures/RBT_Set.thy

Relationship to 2-3-4 trees

Red-black trees

datatype *color* = *Red* | *Black*

datatype

'a rbt = *Leaf* | *Node color ('a tree) 'a ('a tree)*

Abbreviations:

$\langle \rangle \equiv \textit{Leaf}$
 $\langle c, l, a, r \rangle \equiv \textit{Node } c \textit{ l a r}$
 $R \textit{ l a r} \equiv \textit{Node Red l a r}$
 $B \textit{ l a r} \equiv \textit{Node Black l a r}$

Color

color :: 'a rbt \Rightarrow color

color $\langle \rangle$ = Black

color $\langle c, -, -, - \rangle$ = *c*

paint :: color \Rightarrow 'a rbt \Rightarrow 'a rbt

paint *c* $\langle \rangle$ = $\langle \rangle$

paint *c* $\langle -, l, a, r \rangle$ = $\langle c, l, a, r \rangle$

Invariants

$rbt :: 'a\ rbt \Rightarrow bool$

$rbt\ t = (invc\ t \wedge invh\ t \wedge color\ t = Black)$

$invc :: 'a\ rbt \Rightarrow bool$

$invc\ \langle \rangle = True$

$invc\ \langle c, l, _, r \rangle =$

$(invc\ l \wedge invc\ r \wedge$

$(c = Red \longrightarrow color\ l = Black \wedge color\ r = Black))$

Invariants

$invh :: 'a\ rbt \Rightarrow bool$

$invh \langle \rangle = True$

$invh \langle -, l, -, r \rangle = (invh\ l \wedge invh\ r \wedge bh(l) = bh(r))$

$bheight :: 'a\ rbt \Rightarrow nat$

$bh(\langle \rangle) = 0$

$bh(\langle c, l, -, - \rangle) =$

$(if\ c = Black\ then\ bh(l) + 1\ else\ bh(l))$

Exercise

Is *invh* what we want?

Define a function $Bpl :: 'a\ rbt \Rightarrow nat\ set$
such that $Bpl\ t$ (“black path lengths”) is the set of all n
such that there is a path from the root of t to a leaf that
contains exactly n black nodes.

Prove $invh\ t \implies Bpl\ t = \{bh(t)\}$

Logarithmic height

Lemma

$$rbt\ t \implies h(t) \leq 2 * \log_2 |t|_1$$

Insertion

$insert :: 'a \Rightarrow 'a\ rbt \Rightarrow 'a\ rbt$

$insert\ x\ t = paint\ Black\ (ins\ x\ t)$

$ins :: 'a \Rightarrow 'a\ rbt \Rightarrow 'a\ rbt$

$ins\ x\ \langle \rangle = R\ \langle \rangle\ x\ \langle \rangle$

$ins\ x\ (B\ l\ a\ r) = (\text{case } cmp\ x\ a\ \text{of}$
 $LT \Rightarrow baliL\ (ins\ x\ l)\ a\ r$
 $| EQ \Rightarrow B\ l\ a\ r$
 $| GT \Rightarrow baliR\ l\ a\ (ins\ x\ r))$

$ins\ x\ (R\ l\ a\ r) = (\text{case } cmp\ x\ a\ \text{of}$
 $LT \Rightarrow R\ (ins\ x\ l)\ a\ r$
 $| EQ \Rightarrow R\ l\ a\ r$
 $| GT \Rightarrow R\ l\ a\ (ins\ x\ r))$

Adjusting colors

$ins\ x\ (B\ l\ a\ r) = \dots\ bal\ (ins\ x\ l)\ a\ r\ \dots\ bal\ l\ a\ (ins\ x\ r)\ \dots$

$bal\ iL, bal\ iR :: 'a\ rbt \Rightarrow 'a \Rightarrow 'a\ rbt \Rightarrow 'a\ rbt$

- Combine arguments $l\ a\ r$ into tree, ideally $\langle l, a, r \rangle$
- Treat invariant violation **Red-Red** in l/r

$bal\ iL\ (R\ (R\ t_1\ a_1\ t_2)\ a_2\ t_3)\ a_3\ t_4 =$

$R\ (B\ t_1\ a_1\ t_2)\ a_2\ (B\ t_3\ a_3\ t_4)$

$bal\ iL\ (R\ t_1\ a_1\ (R\ t_2\ a_2\ t_3))\ a_3\ t_4 =$

$R\ (B\ t_1\ a_1\ t_2)\ a_2\ (B\ t_3\ a_3\ t_4)$

- Principle: replace **Red-Red** by **Red-Black**
- Last equation: $bal\ iL\ l\ a\ r = B\ l\ a\ r$
- Symmetric: $bal\ iR$

Correctness via sorted lists

Lemma

$$\begin{aligned} \text{inorder} (\text{baliL } l \ a \ r) &= \text{inorder } l \ @ \ a \ \# \ \text{inorder } r \\ \text{inorder} (\text{baliR } l \ a \ r) &= \text{inorder } l \ @ \ a \ \# \ \text{inorder } r \end{aligned}$$

Lemma

$$\begin{aligned} \text{sorted} (\text{inorder } t) &\implies \\ \text{inorder} (\text{ins } x \ t) &= \text{ins_list } x \ (\text{inorder } t) \end{aligned}$$

Corollary

$$\begin{aligned} \text{sorted} (\text{inorder } t) &\implies \\ \text{inorder} (\text{insert } x \ t) &= \text{ins_list } x \ (\text{inorder } t) \end{aligned}$$

Proofs easy!

Preservation of invariant

Theorem

$$rbt\ t \implies rbt\ (insert\ x\ t)$$

Chapter 3

Priority Queues

⑨ Priority Queues

⑩ Leftist Heap

⑪ Skew Heap

⑫ Priority Queues Based on Braun Trees

⑨ Priority Queues

⑩ Leftist Heap

⑪ Skew Heap

⑫ Priority Queues Based on Braun Trees

Priority queue informally

Collection of elements with priorities

Operations:

- empty
- emptiness test
- insert
- get element with minimal priority
- delete element with minimal priority

We focus on the priorities:

element = priority

Priority queues are multisets

The same element can be contained **multiple times**
in a priority queue



The abstract view of a priority queue is a **multiset**

Multisets in Isabelle

```
Import "Library/Multiset"
```


Interface of implementation

The type of elements (= priorities) $'a$ is a linear order

An implementation of a priority queue of elements of type $'a$ must provide

- An implementation type $'q$
- $empty :: 'q$
- $is_empty :: 'q \Rightarrow bool$
- $insert :: 'a \Rightarrow 'q \Rightarrow 'q$
- $get_min :: 'q \Rightarrow 'a$
- $del_min :: 'q \Rightarrow 'q$

More operations

- *merge* :: 'q ⇒ 'q ⇒ 'q
Often provided
- decrease key/priority
Not easy in functional setting

Correctness of implementation

A priority queue represents a **multiset** of priorities.
Correctness proof requires:

Abstraction function: $mset :: 'q \Rightarrow 'a \text{ multiset}$

Invariant: $invar :: 'q \Rightarrow bool$

Correctness of implementation

Must prove $\text{invar } q \implies$

$\text{mset empty} = \{\#\}$

$\text{is_empty } q = (\text{mset } q = \{\#\})$

$\text{mset } (\text{insert } x \ q) = \text{mset } q + \{\#x\#\}$

$\text{mset } (\text{del_min } q) = \text{mset } q - \{\#\text{get_min } q\#\}$

$q \neq \text{empty} \implies$

$\text{get_min } q \in \text{set } q \wedge (\forall x \in \text{set } q. \text{get_min } q \leq x)$

where $\text{set } q = \text{set_mset } (\text{mset } q)$

invar empty

$\text{invar } (\text{insert } x \ q)$

$\text{invar } (\text{del_min } q)$

Terminology

A tree is a **heap** if for every subtree the root is \geq all elements in the subtrees.

The term “heap” is frequently used synonymously with “priority queue”.

Priority queue via heap

- $empty = \langle \rangle$
- $is_empty\ h = (h = \langle \rangle)$
- $get_min\ \langle -, a, - \rangle = a$
- Assume we have $merge$
- $insert\ a\ t = merge\ \langle \langle \rangle, a, \langle \rangle \rangle\ t$
- $del_min\ \langle l, a, r \rangle = merge\ l\ r$

Priority queue via heap

A naive merge:

$$\begin{aligned} \text{merge } t_1 \ t_2 &= (\text{case } (t_1, t_2) \text{ of} \\ & \langle \rangle, - \Rightarrow t_2 \mid \\ & -, \langle \rangle \Rightarrow t_1 \mid \\ & \langle l_1, a_1, r_1 \rangle, \langle l_2, a_2, r_2 \rangle \Rightarrow \\ & \quad \text{if } a_1 \leq a_2 \text{ then } \langle \text{merge } l_1 \ r_1, a_1, t_2 \rangle \\ & \quad \text{else } \langle t_1, a_2, \text{merge } l_2 \ r_2 \rangle \end{aligned}$$

Challenge: how to maintaining some kind of balance

9 Priority Queues

10 Leftist Heap

11 Skew Heap

12 Priority Queues Based on Braun Trees

Data_Structures/Leftist_Heap.thy

Leftist tree informally

The **rank** of a tree is the depth of the rightmost leaf.

In a **leftist tree**, the rank of every left child is \geq the rank of its right sibling

Implementation type

datatype

$'a \text{ heap} = \text{Leaf} \mid \text{Node } \text{nat } ('a \text{ tree}) 'a ('a \text{ tree})$

Abbreviations $\langle \rangle$ and $\langle h, l, a, r \rangle$ as usual

Abstraction function:

$\text{mset_tree} :: 'a \text{ heap} \Rightarrow 'a \text{ multiset}$

$\text{mset_tree } \langle \rangle = \{\#\}$

$\text{mset_tree } \langle -, l, a, r \rangle =$

$\{\#a\# \} + \text{mset_tree } l + \text{mset_tree } r$

Heap

$heap :: 'a \text{ lheap} \Rightarrow \text{bool}$

$heap \langle \rangle = \text{True}$

$heap \langle -, l, a, r \rangle = (heap\ l \wedge heap\ r \wedge$
 $(\forall x \in \# \text{ mset_tree } l + \text{ mset_tree } r. a \leq x))$

Leftist tree

$rank :: 'a\ lheap \Rightarrow nat$

$rank \langle \rangle = 0$

$rank \langle -, -, -, r \rangle = rank\ r + 1$

Node $\langle n, l, a, r \rangle$: $n = rank$ of node

$ltree :: 'a\ lheap \Rightarrow bool$

$ltree \langle \rangle = True$

$ltree \langle n, l, -, r \rangle =$

$(n = rank\ r + 1 \wedge rank\ r \leq rank\ l \wedge ltree\ l \wedge ltree\ r)$

Leftist heap invariant

$$\textit{invar } h = (\textit{heap } h \wedge \textit{ltree } h)$$

Why leftist tree?

Lemma *ltree* $t \implies 2^{\text{rank } t} \leq |t|_1$

Lemma Execution time of *merge* t_1 t_2 is bounded by $\text{rank } t_1 + \text{rank } t_2$

merge

Principle: descend on the right

merge $\langle \rangle t_2 = t_2$

merge $t_1 \langle \rangle = t_1$

merge $\langle n_1, l_1, a_1, r_1 \rangle \langle n_2, l_2, a_2, r_2 \rangle =$

(if $a_1 \leq a_2$ then *node* $l_1 a_1$ (*merge* $r_1 \langle n_2, l_2, a_2, r_2 \rangle$))
else *node* $l_2 a_2$ (*merge* $r_2 \langle n_1, l_1, a_1, r_1 \rangle$))

node $:: 'a \text{ lheap} \Rightarrow 'a \Rightarrow 'a \text{ lheap} \Rightarrow 'a \text{ lheap}$

node $l a r =$

(let $rl = rk\ l; rr = rk\ r$

in if $rr \leq rl$ then $\langle rr + 1, l, a, r \rangle$ else $\langle rl + 1, r, a, l \rangle$)

where $rk\ \langle n, -, -, - \rangle = n$

merge

$merge \langle n_1, l_1, a_1, r_1 \rangle \langle n_2, l_2, a_2, r_2 \rangle =$
(if $a_1 \leq a_2$ then node $l_1 a_1 (merge r_1 \langle n_2, l_2, a_2, r_2 \rangle)$
else node $l_2 a_2 (merge r_2 \langle n_1, l_1, a_1, r_1 \rangle)$)

Function *merge* terminates because
decreases with every recursive call.

Functional correctness proofs

including preservation of *invar*

Straightforward

Logarithmic complexity

Complexity measures t_{merge} , t_{insert} t_{del_min} :
count calls of $merge$.

Lemma $t_{merge} l r \leq rank l + rank r + 1$

Lemma $ltree l \wedge ltree r \implies$
 $t_{merge} l r \leq \log_2 |l|_1 + \log_2 |r|_1 + 1$

Lemma

$ltree t \implies t_{insert} x t \leq \log_2 |t|_1 + 2$

Lemma

$ltree t \implies t_{del_min} t \leq 2 * \log_2 |t|_1 + 1$

Can we avoid the rank info in each node?

9 Priority Queues

10 Leftist Heap

11 Skew Heap

12 Priority Queues Based on Braun Trees

Archive of Formal Proofs

https:

`//www.isa-afp.org/entries/Skew_Heap.shtml`

Note: *merge* is called *meld*

Implementation type

Ordinary binary trees

Invariant: *heap*

meld

Principle: swap subtrees when descending

```
meld  $h_1$   $h_2$  =  
(case  $h_1$  of  
   $\langle \rangle \Rightarrow h_2$   
  |  $\langle l_1, a_1, r_1 \rangle \Rightarrow$   
    case  $h_2$  of  
       $\langle \rangle \Rightarrow h_1$   
      |  $\langle l_2, a_2, r_2 \rangle \Rightarrow$   
        if  $a_1 \leq a_2$  then  $\langle \textit{meld } h_2 \ r_1, a_1, l_1 \rangle$   
        else  $\langle \textit{meld } h_1 \ r_2, a_2, l_2 \rangle$ )
```

Function *meld* terminates because ...

Functional correctness proofs

including preservation of *heap*

Straightforward

Logarithmic complexity

Amortized only:

Theorem A sequence of n *insert*, *del_min* and *meld* operations runs in time $O(n * \log n)$.



Average cost of each operation is $O(\log n)$
(even in the worst case)

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https://www.isa-afp.org/entries/Priority_Queue_Braun.shtml

What is a Braun tree?

braun :: 'a tree \Rightarrow bool

braun $\langle \rangle$ = True

braun $\langle l, x, r \rangle$ =

$(|r| \leq |l| \wedge |l| \leq \text{Suc } |r| \wedge \text{braun } l \wedge \text{braun } r)$

Lemma *braun* $t \implies 2^{h(t)} \leq 2 * |t| + 1$

Priority queue implementation

Implementation type: ordinary binary trees

Invariants: *heap* and *braun*

No *merge* — *insert* and *del_min* defined explicitly

insert

insert :: 'a ⇒ 'a tree ⇒ 'a tree

insert a ⟨⟩ = ⟨⟨⟩, a, ⟨⟩⟩

insert a ⟨l, x, r⟩ =

(if $a < x$ then ⟨*insert* x r, a, l⟩ else ⟨*insert* a r, x, l⟩)

Correctness and preservation of invariant straightforward.

del_min

del_min :: 'a tree \Rightarrow 'a tree

del_min $\langle \rangle$ = $\langle \rangle$

del_min $\langle \langle \rangle, x, r \rangle$ = $\langle \rangle$

del_min $\langle l, x, r \rangle$ =

(let (y, l') = *del_left* l in *sift_down* r y l')

sift_down

sift_down :: 'a tree \Rightarrow 'a \Rightarrow 'a tree \Rightarrow 'a tree

sift_down $\langle \rangle$ a $\langle \rangle$ = $\langle \langle \rangle, a, \langle \rangle \rangle$

sift_down $\langle \langle \rangle, x, \langle \rangle \rangle$ a $\langle \rangle$ =

(if $a \leq x$ then $\langle \langle \langle \rangle, x, \langle \rangle \rangle, a, \langle \rangle \rangle$

else $\langle \langle \langle \rangle, a, \langle \rangle \rangle, x, \langle \rangle \rangle$)

sift_down $\langle l_1, x_1, r_1 \rangle$ a $\langle l_2, x_2, r_2 \rangle$ =

(if $a \leq x_1 \wedge a \leq x_2$ then $\langle \langle l_1, x_1, r_1 \rangle, a, \langle l_2, x_2, r_2 \rangle \rangle$

else if $x_1 \leq x_2$ then $\langle \text{sift_down } l_1 \text{ a } r_1, x_1, \langle l_2, x_2, r_2 \rangle \rangle$

else $\langle \langle l_1, x_1, r_1 \rangle, x_2, \text{sift_down } l_2 \text{ a } r_2 \rangle$)

Functional correctness proofs for deletion

including preservation of *heap* and *braun*

Many lemmas, mostly straightforward

Logarithmic complexity

Running time of *insert*, *del_left* and *sift_down* (and therefore *del_min*) bounded by height

Remember: *braun* $t \implies 2^{h(t)} \leq 2 * |t| + 1$

\implies

Above running times logarithmic in size

Sorting with priority queue

$pq [] = empty$

$pq (x\#xs) = insert\ x\ (pq\ xs)$

$mins\ q =$

(if $is_empty\ q$ then $[]$

else $get_min\ h\ \# mins\ (del_min\ h)$)

$sort_pq = mins \circ pq$

Complexity of $sort$: $O(n \log n)$

if all priority queue functions have complexity $O(\log n)$

Sorting with priority queue

$pq [] = \text{empty}$

$pq (x\#xs) = \text{insert } x (pq\ xs)$

Not optimal. Linear time possible.