Semantics of Programming Lectures

Exercise Sheet 5

Exercise 5.1 Program Equivalence

Let Or be the disjunction of two bexps:

```
definition Or :: "bexp \Rightarrow bexp \Rightarrow bexp" where "Or \ b1 \ b2 = Not \ (And \ (Not \ b1) \ (Not \ b2))"
```

Prove or disprove (by giving counterexamples) the following program equivalences.

- 1. IF And b1 b2 THEN c1 ELSE c2 \sim IF b1 THEN IF b2 THEN c1 ELSE c2 ELSE c2
- 2. WHILE And b1 b2 DO $c \sim$ WHILE b1 DO WHILE b2 DO c
- 3. WHILE And b1 b2 DO $c \sim$ WHILE b1 DO c; WHILE And b1 b2 DO c
- 4. WHILE Or b1 b2 DO $c \sim$ WHILE Or b1 b2 DO c;; WHILE b1 DO c

Exercise 5.2 Nondeterminism

In this exercise we extend our language with nondeterminism. We will define nondeterministic choice (c_1 OR c_2), that decides nondeterministically to execute c_1 or c_2 ; and assumption (ASSUME b), that behaves like SKIP if b evaluates to true, and returns no result otherwise.

- 1. Modify the datatype com to include the new commands OR and ASSUME.
- 2. Adapt the big step semantics to include rules for the new commands.
- 3. Prove that c_1 OR $c_2 \sim c_2$ OR c_1 .
- 4. Prove: (IF b THEN c1 ELSE c2) \sim ((ASSUME b; c1) OR (ASSUME (Not b); c2))

Note: It is easiest if you take the existing theories and modify them.

Exercise 5.3 Deskip

Define a recursive function

```
fun deskip :: "com \Rightarrow com"
```

that eliminates as many SKIPs as possible from a command. For example:

```
deskip (SKIP;; WHILE b DO (x := a;; SKIP)) = WHILE b DO x := a
```

Prove its correctness by induction on c:

Hint: Take a look at SkipE and sim_while_cong.

lemma " $deskip\ c \sim c$ "

Homework 5.1 Control Flow Graphs

Submission until Sunday, November 28, 23:59pm.

In this homework, we want to study the concept of *control flow graphs* for IMP and connect it to the small-step semantics.

A control flow graph is a labeled transition system, where the edges are labeled with *effects*. An effect is a partial function on states, returning *None* when the test for a Boolean condition fails:

```
type_synonym effect = "state \Rightarrow state \ option"
type_synonym 'q \ cfg = "('q,effect) \ lts"
```

Intuitively, the control flow graph is executed by following a path and applying the effects of the actions to the state. Lift effects to paths. Only paths where all tests succeed shall yield a result $\neq None$.

```
fun eff_list :: "effect list <math>\Rightarrow state \Rightarrow state \ option"
```

The control flow graph of a WHILE-Program can be defined over nodes that are commands. Complete the following definition. (*Hint:* Have a look at the small-step semantics first)

```
inductive cfg :: "com \ cfg" where cfg\_assign: "cfg \ (x ::= a) \ (\lambda s. \ Some \ (s(x:=aval \ a \ s))) \ (SKIP)" | cfg\_Seq2: "cfg \ c1 \ e \ c1' \Longrightarrow cfg \ (c1;;c2) \ e \ (c1';;c2)"
```

We want to show that the effects of paths in the CFG match the small-step semantics. Prove the theorem for a single step first:

```
theorem eq\_step: "(c,s) \rightarrow (c',s') \longleftrightarrow (\exists e. \ cfg \ c \ e' \land e \ s = Some \ s')"
```

Now prove the main theorem:

```
theorem eq\_path: "(c,s) \rightarrow * (c',s') \longleftrightarrow (\exists \pi. word \ cfg \ c \ \pi \ c' \land eff\_list \ \pi \ s = Some \ s')"
```

Homework 5.2 Resource management

Submission until Sunday, November 28, 23:59pm.

Frequently, programs need to allocate resources and clean them up afterwards, even in case of exceptions. Extend IMP with such constructs:

- THROW indicates that there is an error
- ATTEMPT c_1 CLEANUP c_2 executes c_1 until and exception is thrown and always executes c_2 .

The detailed semantics of these constructs are as follows.

Command THROW throws an exception. The only command that can catch an exception is ATTEMPT c_1 CLEANUP c_2 : if an exception is thrown by c_1 , execution stops there and continues with c_2 . If no exception is thrown, c_2 is also executed. An exception being thrown during c_2 aborts execution of c_2 and propagates "upwards" to the next ATTEMPT block.

Similarly to the small-step semantics, the big-step semantics is now of type $com \times state \Rightarrow com \times state$. In a big step $(c,s) \Rightarrow (x,t)$, x is THROW if an exception has been thrown, otherwise it is SKIP.

Copy existing types and definitions from Big_Step and adapt them.

Step 1 Define the modified big-step semantics.

```
inductive big\_step :: "com \times state \Rightarrow com \times state \Rightarrow bool" (infix "\infty" 55)
```

Step 2 Adapt the previous auxiliary setup from the *BigStep* theory, including rule inversion.

We will also need the introduction & induction rules:

```
\label{lemmas} \begin{array}{ll} \textbf{lemmas} \ big\_step\_induct = big\_step.induct[split\_format(complete)] \\ \textbf{declare} \ big\_step.intros[intro] \\ \end{array}
```

Step 3 Prove that (\Rightarrow) always produces *SKIP* or *THROW*.

```
lemma big\_step\_result: "(c,s) \Rightarrow (c',s') \Longrightarrow (c' = SKIP \lor c' = THROW)"
```

Step 4 The small-step semantics can also be adjusted. It has the same type as before, but instead of having only SKIP as the final command, we can also have THROW. Exceptions propagate upwards until an enclosing ATTEMPT is found, that is, until a configuration (ATTEMPT THROW CLEANUP c, s) is reached.

Define the modified small-step semantics and prove that it is complete wrt to the big-step semantics.

```
inductive small\_step :: "com * state \Rightarrow com * state \Rightarrow bool" (infix "\rightarrow" 55)
```

```
abbreviation small\_steps :: "com * state \Rightarrow com * state \Rightarrow bool" (infix "\rightarrow*" 55) where "x \rightarrow * y == star \ small\_step \ x \ y"
```

 ${\bf declare}\ small_step.intros[simp,intro]$

You may need some lemmas from the existing theories. In addition, you might need a new lemma about $x \to *y$ and ATTEMPT.

lemma big_to_small : " $cs \Rightarrow xt \Longrightarrow cs \rightarrow *xt$ "