

Semantics of Programming Languages

Exercise Sheet 10

Exercise 10.1 Hoare Logic

In this exercise, you shall prove correct some Hoare triples.

Step 1 Write a program that stores the maximum of the values of variables a and b in variable c .

definition $Max :: \text{“com”}$

Step 2 Show that $Tut.Max$ satisfies the following Hoare triple:

lemma $\text{“} \vdash \{ \lambda s. True \} Max \{ \lambda s. s \text{“}c\text{”} = max (s \text{“}a\text{”}) (s \text{“}b\text{”}) \} \text{”}$

Step 3 Now define a program MUL that returns the product of x and y in variable z . You may assume that y is not negative.

definition $MUL :: \text{“com”}$

Step 4 Prove that MUL does the right thing.

lemma $\text{“} \vdash \{ \lambda s. 0 \leq s \text{“}y\text{”} \} MUL \{ \lambda s. s \text{“}z\text{”} = s \text{“}x\text{”} * s \text{“}y\text{”} \} \text{”}$

Hints:

- You may want to use the lemma *algebra_simps*, containing some useful lemmas like distributivity.
- Note that we use a backward assignment rule. This implies that the best way to do proofs is also backwards, i.e., on a semicolon $c_1; c_2$, you first continue the proof for c_2 , thus instantiating the intermediate assertion, and then do the proof for c_1 . However, the first premise of the *Seq*-rule is about c_1 . In an Isar proof, this is no problem. In an **apply**-style proof, the ordering matters. Hence, you may want to use the *[rotated]* attribute:

lemmas $Seq_bwd = Seq[rotated]$

lemmas $hoare_rule[intro?] = Seq_bwd Assign Assign' If$

Step 5 Note that our specifications still have a problem, as programs are allowed to overwrite arbitrary variables.

For example, regard the following (wrong) implementation of *Tut.Max*:

definition “ $MAX_wrong = (\"a\" ::= N 0;; \"b\" ::= N 0;; \"c\" ::= N 0)$ ”

Prove that *MAX_wrong* also satisfies the specification for *Tut.Max*:

lemma “ $\vdash \{\lambda s. True\} MAX_wrong \{\lambda s. s \"c\" = max (s \"a\") (s \"b\")\}$ ”

What we really want to specify is, that *Tut.Max* computes the maximum of the values of *a* and *b* in the initial state. Moreover, we may require that *a* and *b* are not changed. For this, we can use logical variables in the specification. Prove the following more accurate specification for *Tut.Max*:

lemma “ $\vdash \{\lambda s. a=s \"a\" \wedge b=s \"b\"\} Max \{\lambda s. s \"c\" = max a b \wedge a = s \"a\" \wedge b = s \"b\"\}$ ”

The specification for *MUL* has the same problem. Fix it!

Homework 10.1 A Hoare Calculus with Execution Times

Submission until Monday, Jan 15, 23:59pm.

In this homework, we will consider a Hoare calculus with execution times.

Step 1 We first give a modified big-step semantics to account for execution times. A judgement of the form $(c, s) \Rightarrow^{\hat{n}} t$ has the intended meaning that we can get from state *s* to state *t* by an terminating execution of program *c* that takes exactly *n* time steps:

$(SKIP, s) \Rightarrow^{\hat{1}} s$

$(x ::= a, s) \Rightarrow^{\hat{1}} s[a/x]$

$\llbracket (c_1, s_1) \Rightarrow^{\hat{n}_1} s_2; (c_2, s_2) \Rightarrow^{\hat{n}_2} s_3; n_1 + n_2 = n_3 \rrbracket \implies (c_1;; c_2, s_1) \Rightarrow^{\hat{n}_3} s_3$

$\llbracket bval b s; (c_1, s) \Rightarrow^{\hat{n}_1} t; n_3 = Suc n_1 \rrbracket \implies (IF b THEN c_1 ELSE c_2, s) \Rightarrow^{\hat{n}_3} t$

$\llbracket \neg bval b s; (c_2, s) \Rightarrow^{\hat{n}_2} t; n_3 = Suc n_2 \rrbracket \implies (IF b THEN c_1 ELSE c_2, s) \Rightarrow^{\hat{n}_3} t$

$\neg bval b s \implies (WHILE b DO c, s) \Rightarrow^{\hat{1}} s$

$\llbracket bval b s_1; (c, s_1) \Rightarrow^{\hat{n}_1} s_2; (WHILE b DO c, s_2) \Rightarrow^{\hat{n}_2} s_3; n_1 + n_2 + 1 = n_3 \rrbracket \implies (WHILE b DO c, s_1) \Rightarrow^{\hat{n}_3} s_3$

Step 2 Some theoretical background: We need *extended natural numbers*. These are provided by the *HOL-Library.Extended_Nat* theory. We can imagine extended natural numbers as the union of all natural numbers \mathbf{N} and ∞ . Here are some examples to illustrate their arithmetic behaviour:

value “ $3::\text{enat}$ ” — 3
value “ $\infty::\text{enat}$ ” — ∞
value “ $(3::\text{enat}) + 4$ ” — 7
value “ $(3::\text{enat}) + \infty$ ” — ∞
value “ $eSuc\ 3$ ” — 4
value “ $eSuc\ \infty$ ” — ∞

Step 3 Next, we define a Hoare calculus that also accounts for execution times. Assertions are still the same (of type $state \Rightarrow bool$), but we introduce new *quantitative assertions* of type $state \Rightarrow \text{enat}$.

type_synonym *assn* = “ $state \Rightarrow bool$ ”
type_synonym *qassn* = “ $state \Rightarrow \text{enat}$ ”

It is thought that the result of a *qassn* represents a *potential*, where ∞ corresponds to a *False* assertion in classical Hoare calculus. We can hence embed assertions into quantitative assertions:

\downarrow *False* = ∞
 \downarrow *True* = 0

We can define what it means for a quantitative Hoare triple to be valid:

$(\models_Q \{P\} c \{Q\}) = (\forall s. P\ s < \infty \longrightarrow (\exists t p. (c, s) \Rightarrow \widehat{p}\ t \wedge \text{enat}\ p + Q\ t \leq P\ s))$

Finally, we define quantitative Hoare judgements. The idea is that both pre- and post-condition assign an *enat* to a state that is then decreased as the execution progresses. We will see an example in the next step.

inductive *hoareQ* :: “ $qassn \Rightarrow com \Rightarrow qassn \Rightarrow bool$ ” (“ $\vdash_Q (\{(1_)\} / (_)/ \{(1_)\})$ ” 50) **where**

— Skipping and assignment both decrease the potential.

SkipQ: “ $\vdash_Q \{\lambda s. eSuc\ (P\ s)\} SKIP \{P\}$ ” |
AssignQ: “ $\vdash_Q \{\lambda s. eSuc\ (P\ (s[a/x]))\} x ::= a \{P\}$ ” |

— *IF* *THEN* *ELSE* is a bit tricky: We decrease the potential by one before executing either branch. Then we add 0 to the branch that gets executed and ∞ to the branch that does not get executed. This is similar to how in classical Hoare calculus, the branch that does not get executed gets *False* as precondition.

IfQ: “ $\llbracket \vdash_Q \{\lambda s. P\ s + \downarrow(bval\ b\ s)\} c_1 \{Q\};$
 $\vdash_Q \{\lambda s. P\ s + \downarrow(\neg bval\ b\ s)\} c_2 \{Q\} \rrbracket$
 $\implies \vdash_Q \{\lambda s. eSuc\ (P\ s)\} IF\ b\ THEN\ c_1\ ELSE\ c_2 \{Q\}$ ” |

— Sequence works about as expected.

SeqQ: “ $\llbracket \vdash_Q \{P_1\} c_1 \{P_2\}; \vdash_Q \{P_2\} c_2 \{P_3\} \rrbracket \implies \vdash_Q \{P_1\} c_1;;c_2 \{P_3\}$ ” |

— *WHILE* *DO* is a combination of conditional and sequence. The invariant is also a function to *enat*.

WhileQ:
“ $\vdash_Q \{\lambda s. I\ s + \downarrow(bval\ b\ s)\} c \{\lambda t. I\ t + 1\}$
 $\implies \vdash_Q \{\lambda s. I\ s + 1\} WHILE\ b\ DO\ c \{\lambda s. I\ s + \downarrow(\neg bval\ b\ s)\}$ ” |

— The consequence rule also works like in the classic Hoare calculus.

conseqQ: “ $\llbracket \vdash_Q \{P\} c \{Q\}; \bigwedge s. P s \leq P' s; \bigwedge s. Q' s \leq Q s \rrbracket \implies \vdash_Q \{P'\} c \{Q'\}$ ”

Step 4 To exercise our newly-introduced Hoare calculus with timing, we will prove a Hoare triple for an example program that computes the sum of numbers from 1 to n . However, we are only interested in computing the total runtime and disregard correctness properties.

definition *wsum* :: *com where*

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“wsum =
  "y" ::= N 0;;
  WHILE Less (N 0) (V "x")
  DO ("y" ::= Plus (V "y") (V "x");;
     "x" ::= Plus (V "x") (N (- 1)))”

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The following lemma states that the *wsum* program will take at most $2 + 3 * n$ steps to complete. Prove it!

theorem *wsum*: “ $\vdash_Q \{\lambda s. \text{enat } (2 + 3*n) + \downarrow (s \text{ "x"} = \text{int } n)\} \text{wsum } \{\lambda s. 0\}$ ”

unfolding *wsum_def*

apply(*rule SeqQ[rotated]*)

apply(*rule conseqQ*)

apply(*rule WhileQ[where I = “ $\lambda s. \text{enat } (3 * \text{nat } (s \text{ "x"}))$ ”]*)

Step 5 Your task is to prove soundness. The SKIP-case is already demonstrated below. Prove the remaining extracted lemmas.

lemma *Skip_sound*: “ $\models_Q \{\lambda a. \text{eSuc } (P a)\} \text{SKIP } \{P\}$ ”

unfolding *hoare_Qvalid_def* **proof** (*safe*)

fix *s* **assume** “ $\text{eSuc } (P s) < \infty$ ”

then have “ $(\text{SKIP}, s) \Rightarrow \hat{1} s \wedge \text{enat } 1 + P s \leq \text{eSuc } (P s)$ ”

using *Skip_eSuc_def* **by** (*auto split: enat.splits*)

thus “ $\exists t n. (\text{SKIP}, s) \Rightarrow \hat{n} t \wedge \text{enat } n + P t \leq \text{eSuc } (P s)$ ”

by *blast*

qed

theorem *Assign_sound*: “ $\models_Q \{\lambda b. \text{eSuc } (P (b[a/x]))\} x ::= a \{P\}$ ”

theorem *conseq_sound*:

assumes *hypP*: “ $\bigwedge s. P s \leq P' s$ ”

and *hypQ*: “ $\bigwedge s. Q' s \leq Q s$ ”

and *IH*: “ $\models_Q \{P\} c \{Q\}$ ”

shows “ $\models_Q \{P'\} c \{Q'\}$ ”

theorem *If_sound*:

assumes “ $\models_Q \{\lambda a. P a + \downarrow (b \text{val } b a)\} c_1 \{Q\}$ ”

and “ $\models_Q \{\lambda a. P a + \downarrow (\neg b \text{val } b a)\} c_2 \{Q\}$ ”

shows " $\models_Q \{\lambda a. eSuc (P a)\} IF b THEN c_1 ELSE c_2 \{Q\}$ "

theorem *Seq_sound*:

assumes " $\models_Q \{P_1\} c_1 \{P_2\}$ "

and " $\models_Q \{P_2\} c_2 \{P_3\}$ "

shows " $\models_Q \{P_1\} c_1;;c_2 \{P_3\}$ "

Hint: You'll need to induct over the potential in the last proof – for this, the *less_induct* induction scheme may be helpful.

theorem *While_sound*:

assumes " $\models_Q \{\lambda s. INV s + \downarrow(bval b s)\} c \{\lambda t. INV t + 1\}$ "

shows " $\models_Q \{\lambda s. INV s + 1\} WHILE b DO c \{\lambda s. INV s + \downarrow(\neg bval b s)\}$ "